

# IMGS-616-20141 OPTIONAL HW #9

Due 12/11/2014 (Th): hand directly to me or slide under my office door 76-2112  
(You may submit some or all of problems)

1. The impulse response of an imaging system is:

$$h[x] = \exp \left[ +i\pi \left( \frac{x}{\alpha_0} \right)^2 \right]$$

Evaluate the expression for the inverse filter  $w[x]$

2. The transfer function of a filter is:

$$H_1[\xi] = 1[\xi] \cdot \exp[i \cdot 2\pi \cdot (1 - 2 \cdot \text{RECT}[\xi])]$$

- (a) Characterize this filter (highpass, ...)  
(b) Evaluate and sketch the impulse response  $h[x]$   
Find and sketch the outputs  $g[x]$  for the following inputs:

- (c)

$$f_1[x] = \cos \left[ 2\pi \frac{x}{8} \right]$$

- (d)

$$f_2[x] = \cos[4\pi x]$$

- (e) Repeat (c) and (d) for the modified transfer function:

$$H_2[\xi] = 1[\xi] \cdot \exp \left[ i \cdot 2\pi \cdot \left( \frac{1}{2} - \text{RECT}[\xi] \right) \right]$$

3. The transfer function of a 1-D system is:

$$H[\xi] = \left( 1 - 2 \cdot \text{RECT} \left[ \frac{\xi}{0.5} \right] * \text{COMB}[\xi] \right) \cdot \exp[+i\pi (1 - \text{COMB}[\xi] * \text{RECT}[2\xi])]$$

- (a) Sketch this transfer function as (real, imaginary) parts and as (magnitude, phase).  
(b) Classify this filter (e.g., highpass, ...).  
(c) Derive and sketch the impulse response  $h[x]$ .  
(d) Derive and sketch the inverse filter  $w[x]$  for this impulse response.

4. Determine the areas of:

(a)  $\cos[2\pi x] \cdot \cos[\pi x^2]$

(b)  $\text{SINC}^4[x]$

5. An imaging system acting on the 1-D input function  $f[x]$  includes the following steps:

- (a) evaluate  $\mathcal{F}\{f[x]\}|_{\xi \rightarrow \frac{x}{(\alpha_0)^2}}$  where  $\alpha_0$  is a constant parameter with units of “length”;  
(b) multiply by the real-valued pupil function  $p[x]$  (which has finite support) to form  $g_1[x]$   
(c) evaluate  $\mathcal{F}\{g_1[x]\}|_{\xi \rightarrow \frac{x}{(\alpha_0)^2}}$

For an input function of your choice, evaluate and sketch the output function if the pupil  $p[x] = \text{RECT} \left[ \frac{x}{b_0} \right]$ . Note that this is a real imaging system where the first and last steps propagate light a long distance to the Fraunhofer diffraction region.

6. Modify the imaging system in the previous problem so that the explicit steps in the process are now:

- (a) evaluate  $\mathcal{F}\{f[x]\}|_{\xi \rightarrow \frac{x}{(\alpha_0)^2}}$  where  $\alpha_0$  is a constant parameter with units of “length”;
- (b) multiply by  $p[x] = \text{RECT}\left[\frac{x}{b_0}\right] \cdot \exp\left[-i\pi\left(\frac{x}{\alpha_1}\right)^2\right]$ , where both  $b_0$  and  $\alpha_1$  are system parameters with units of length
- (c) convolve the product in step (b) with impulse response  $h[x] = \exp\left[+i\pi\left(\frac{x}{\alpha_1}\right)^2\right]$

In this system, steps (b) and (c) are the first two steps in an *M-C-M* chirp Fourier transformer. This is also a realistic imaging system step (a) represents propagation from the object to a location in the Fraunhofer diffraction region, step (b) is the action of a lens, and step (c) is propagation to the focal plane of the lens. In this example, the constants  $\alpha_1 = \sqrt{\lambda_0 z_1}$  and  $\alpha_1 = \sqrt{\lambda_0 \mathbf{f}}$ , where  $z_1$  is the propagation distance from the object to the lens and  $\mathbf{f}$  is the focal length of the lens.

7. A measured signal  $g[x]$  is the sum of a deterministic part  $f[x]$  and a “stochastic” random part  $n[x]$

- (a) Describe the constraints on  $f[x]$  AND on  $n[x]$  that would allow a filter  $w[x]$  to be constructed such that the output of the filter is *exactly* equal to  $f[x]$ , i.e.,

$$(f[x] + n[x]) * w[x] = f[x]$$

- (b) Specify AND SKETCH the transfer function AND impulse response of the filter that will “extract”  $f[x]$  from  $g[x]$  if the signal and noise spectra are the functions::

$$\begin{aligned} F[\xi] &= \text{STEP}[\xi] \cdot \exp[+i\pi\xi^2] \\ N[\xi] &= \text{STEP}[-\xi] \cdot \exp[+i\pi \cdot R[\xi]] \end{aligned}$$

where  $R[\xi]$  is a random number selected from the interval  $-\pi \leq R[\xi] < +\pi$

8. We already know that the output of a “perfect” imaging system presented with the input  $f[x]$  is  $f[x]$ :

$$f[x] * \delta[x] = f[x]$$

The output of a second imaging system consists of the sum of two identical but translated replicas of the input, where the two replicas are displaced by the distance  $b_0$ .

- (a) Write down the expression for the impulse response of the second system.
- (b) Evaluate and sketch the outputs for the following inputs:

$$\begin{aligned} f_1[x] &= \cos\left[2\pi\left(\frac{x}{b_0} + \frac{1}{2}\right)\right] \\ f_2[x] &= \cos\left[2\pi\left(\frac{x}{2b_0}\right)\right] \end{aligned}$$

- (c) Evaluate and sketch the transfer function of the system
- (d) Is it possible to extract the input  $f[x]$  from the output  $g[x]$  and the impulse response  $h[x]$ ? Explain why or why not.

9. Modify the previous problem so that the second exposure of the system is attenuated relative to the first by a factor of 2..

10. Modify the problem so that the image is not created from the two exposures but rather from a single exposure made over the displacement by the distance  $b_0$ .