

28 OCTOBER 2009

(1)

MAKEUP CLASS F 10/30 4PM-6PM

HW #7 HAS BEEN POSTED (HW #8 MAY NOT BE FAR BEHIND)

2-D FOURIER

- (1) SEPARABLE
- (2) CIRCULARLY SYMMETRIC (EVEN)

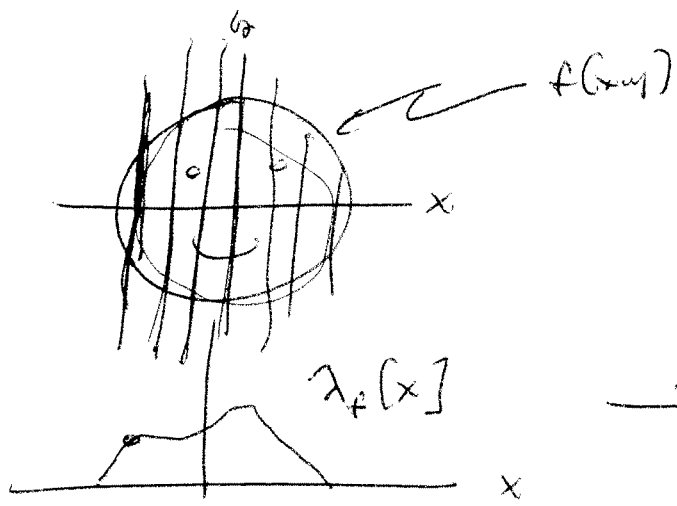
→ (3) RELEVANT TO MANY IMAGING SYSTEMS. (RADON TRANSFORM)

$$F[\xi, \eta] = \iint_{-\infty}^{+\infty} f(x, y) \left(e^{+2\pi i(\xi x + \eta y)} \right) dx dy$$

"PROJECTING $f(x, y)$ ONTO BASIS FUNCTIONS OF CONVOLUTION"
+10 EIGENFUNCTIONS

WHAT IF $F[\xi, 0] = \int_{-\infty}^{+\infty} dx e^{-2\pi i \xi x} \left(\int_{-\infty}^{+\infty} f(x, y) \cdot 1[x, y] dy \right)$
 $\mathcal{F}_f(x)$

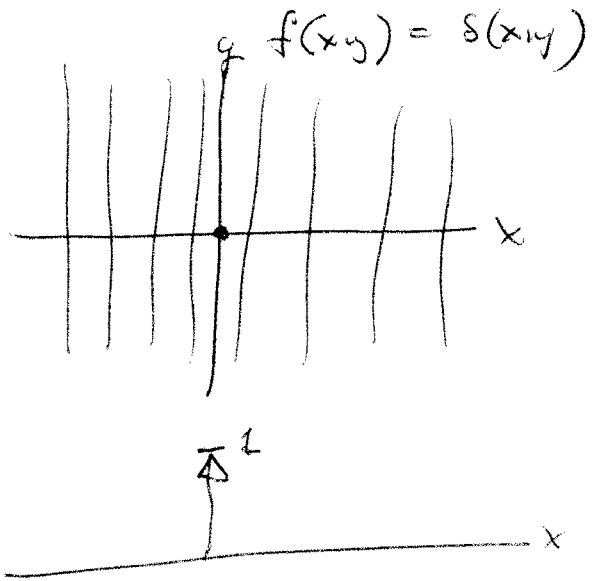
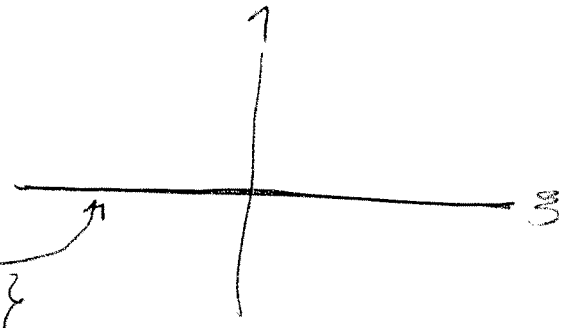
10/28 - (2)



$\int_{x \rightarrow \xi}$

$\int_{x \rightarrow \xi} \{\lambda_f(x)\}$

$= \Delta_f(\xi)$



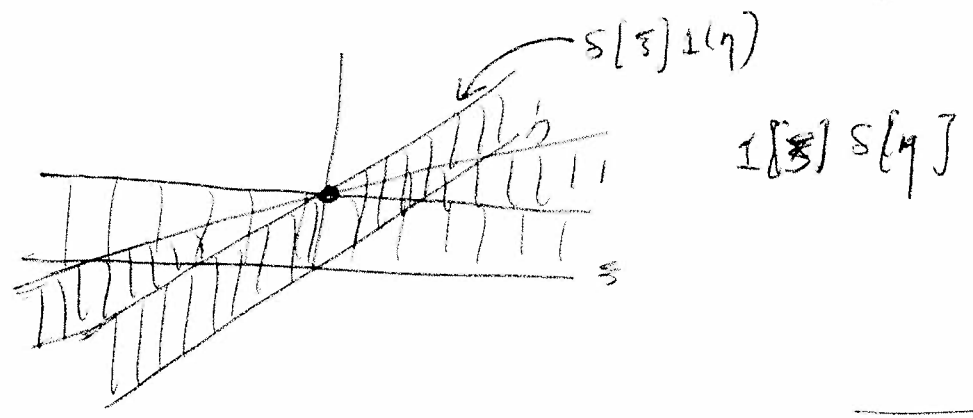
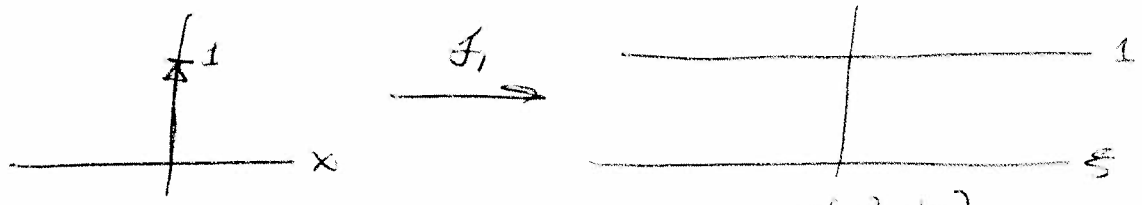
$\int_{-\infty}^{+\infty}$

$\delta(x,y) dy$

$\int_{-\infty}^{+\infty} \delta(x) \delta(y) dy$

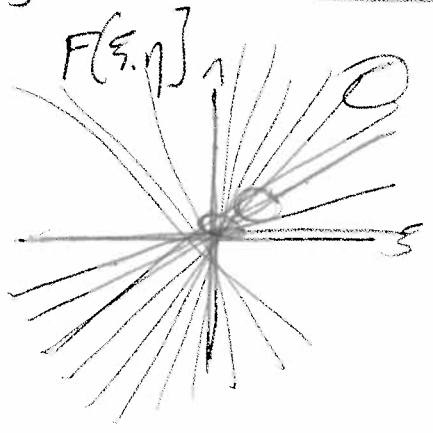
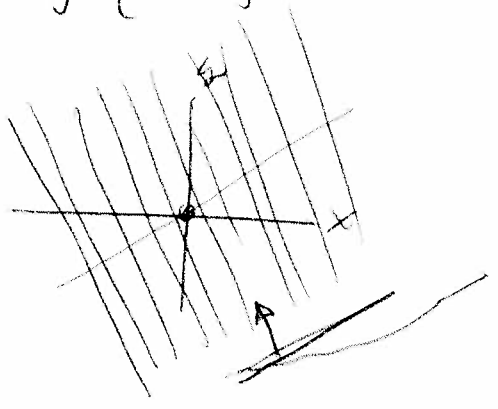
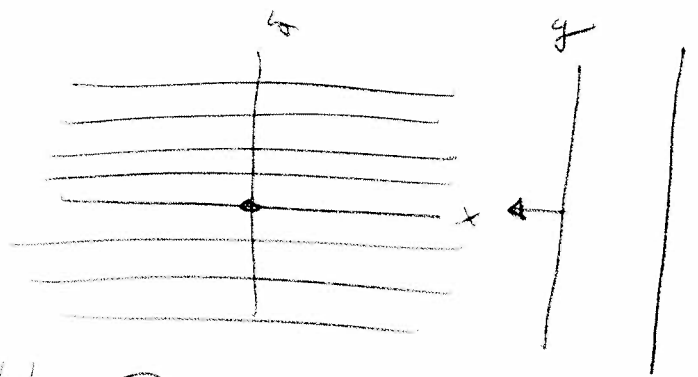
$= \delta(x) \int_{-\infty}^{+\infty} \delta(y) dy = \delta(x) \cdot 1$

10/28 - (3)



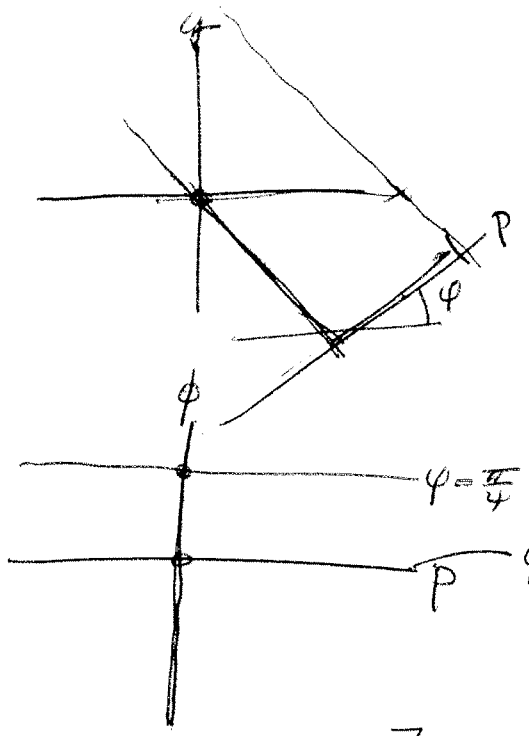
$$F_1 \{ \lambda_+(x) \} \Rightarrow F(\xi, 0)$$

$$x \rightarrow \xi \quad f \{ \delta(x) \} = \perp(\xi, 0)$$

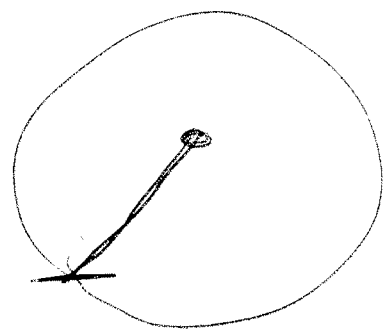


ADD THE 1-D SPECTRA FROM EACH PROJECTION

10/28 - ④



$\lambda_f(x)$
 $\lambda_f(y)$
 PEDAL VECTOR
 $\lambda_f(p, \phi)$
 \uparrow
 λ_f



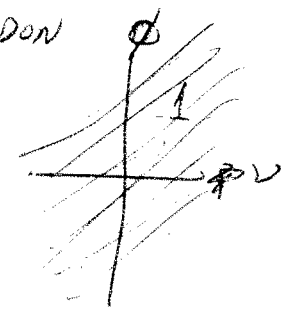
$S[x, y]$ $[p, \phi] \Rightarrow$ SINOGRAM

LINE-INTEGRAL

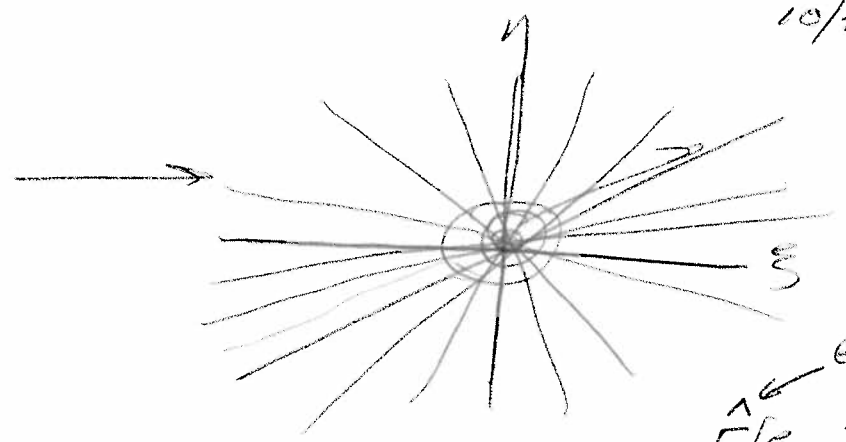
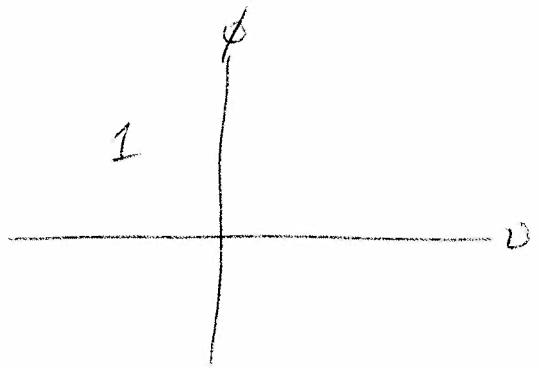
A PROJECTION ONTO ALL DIRECTIONS \Rightarrow RADON TRANSFORM

1917 JOHAN RADON

$$\begin{aligned}
 f(x, y) &\xrightarrow{R_z} \lambda_\phi(p, \phi) \xrightarrow{F} \Delta_f(v, \phi) \\
 S(x, y) &\xrightarrow{\quad} \underline{S(p)} \cdot \underline{1(\phi)} \xrightarrow{\quad} \underline{1(v)} \cdot \underline{1(\phi)}
 \end{aligned}$$



10/20 (5)



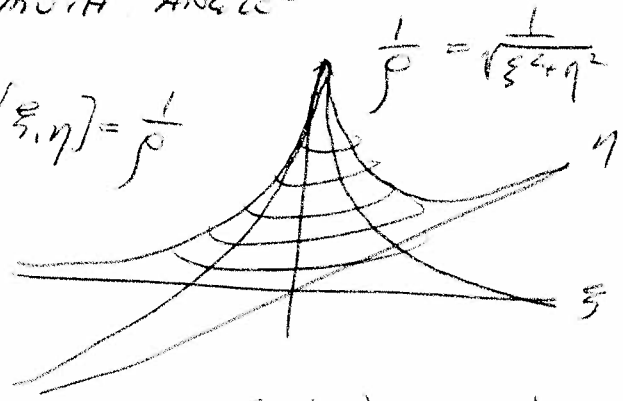
ESTIMATE
 $\hat{F}[\xi, \eta]$

SUM 1-D SPECTRA OVER AZIMUTH ANGLE

$$\hat{F}[\xi, \eta] = \frac{1}{\sqrt{\xi^2 + \eta^2}}$$

ESTIMATE
 OF CONSTANT

$$\hat{F}[\xi, \eta] = \frac{1}{\rho}$$



$$F[\xi, \eta] = \frac{1[\xi, \eta]}{\sqrt{\xi^2 + \eta^2}}$$

$$\hat{F}[\xi, \eta] \xrightarrow{\mathcal{F}_2} \frac{1}{r} \neq \delta(x, y) = \frac{\delta(r)}{2\pi r}$$

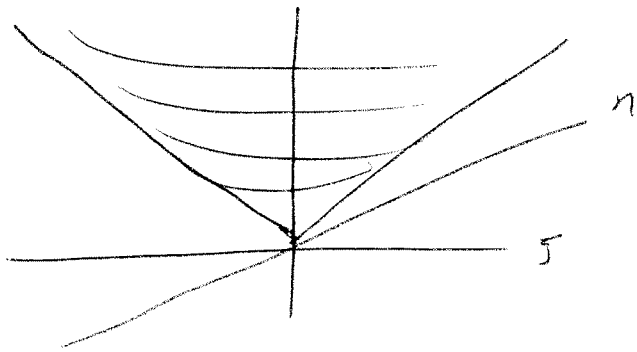
$$\mathcal{F}_2^{-1} \left\{ \frac{1}{\rho} \right\} = \frac{1}{r}$$

$$\frac{1}{r} = \hat{\delta}[x, y] =$$

$$\hat{F}[\xi, \eta] = \frac{1}{\rho} \rightarrow \hat{F}[\xi, \eta] \cdot H[\xi, \eta] = F[\xi, \eta] \left(\sqrt{\xi^2 + \eta^2} \right)$$

$$F[\xi, \eta] = 1[\xi, \eta] \quad H[\xi, \eta] = \sqrt{\xi^2 + \eta^2} = \rho$$

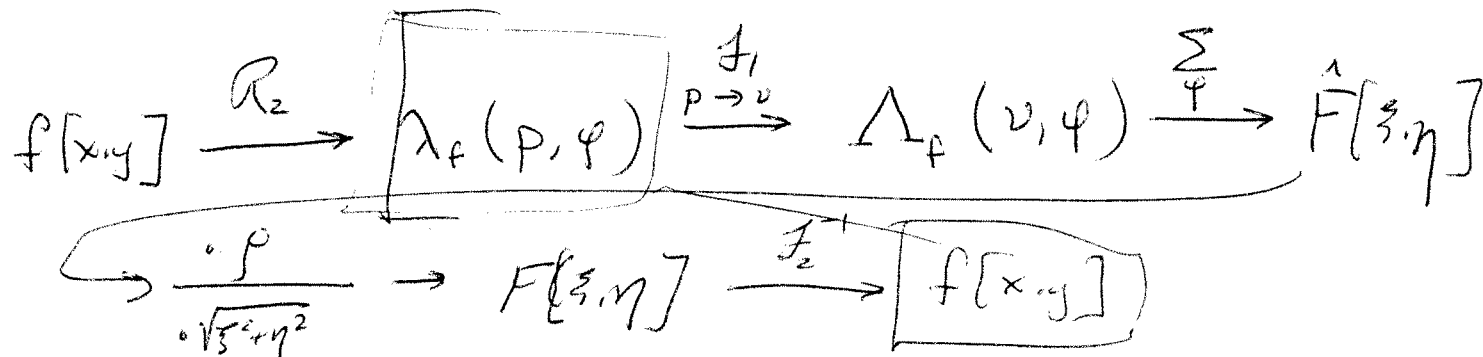
"RHO FILTER" ("HIGH-BOOST" FILTER)



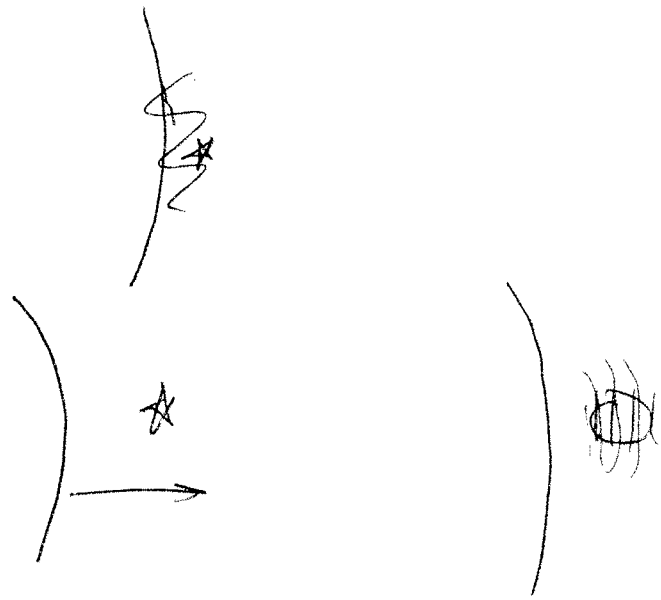
$$H(\rho) = \rho$$

$$H(\xi) = \xi$$

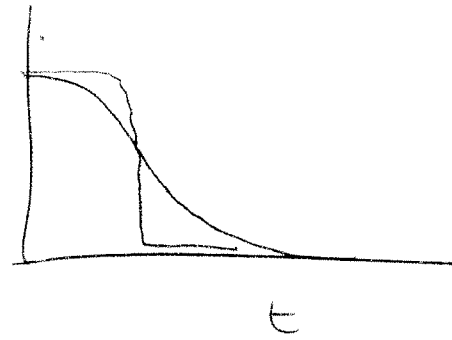
$$h(r)$$



10/28 - ⑦



LIGHT



10/28 - 8

FILTERING TO SOLVE IMAGING TASKS

① DIRECT

$$\mathcal{O}\{f(x)\} = g(x)$$

② INVERSE

$$\mathcal{O}^{-1}\{g(x)\} = f(x)$$

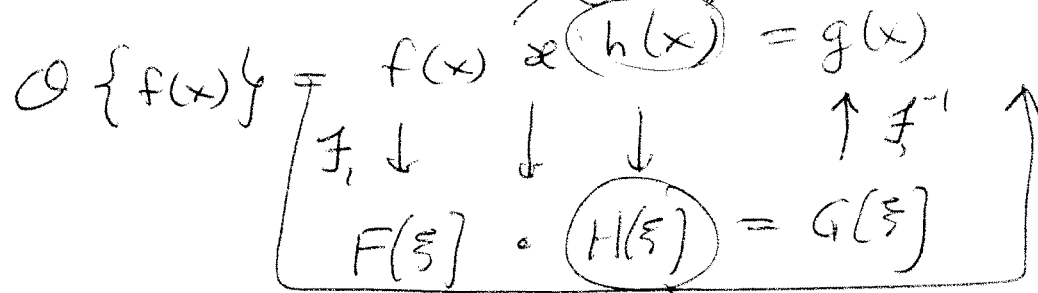
③ ANALYSIS

$$g(x), f(x) \Rightarrow \mathcal{O}$$

OFTEN THE SAME

FILTERING p.s.f

LSI SYSTEM



DIFFERENT CLASSES OF $h(x), H(\xi)$

OTF

$$\text{OTF } H(\xi) = |H(\xi)| e^{i\Phi_H(\xi)}$$

(1) MAGNITUDE FILTERS ($\Phi=0$)

(2) PHASE FILTERS ($|H|=1$)

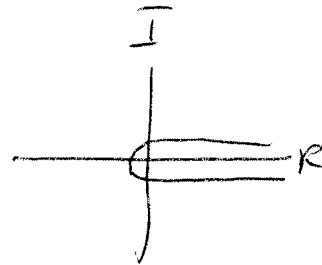
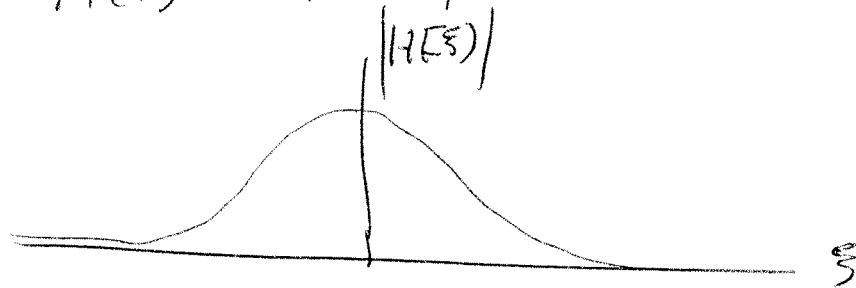
(3) GENERAL CASE

→ INVERSE PROBLEM (WIENER, WIENER-HILSTRUM MATCHED)

MAGNITUDE - ONLY FILTERS

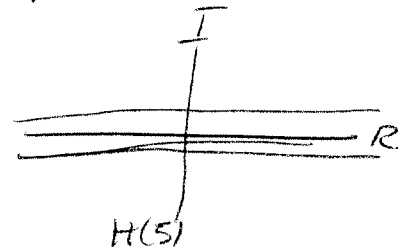
$$\angle H(\xi) = 0(\xi)$$

$$|H(\xi)| = |H(\xi)| \geq 0 \text{ AND REAL}$$



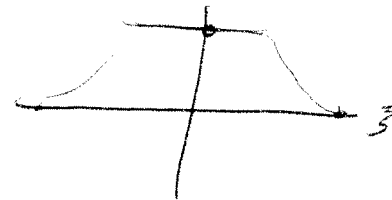
LOOSEN CONSTRAINT $\Rightarrow H(\xi)$ IS REAL

$$\angle = 0, \pm\pi$$



LOWPASS $\Rightarrow H(\xi=0) = 1$

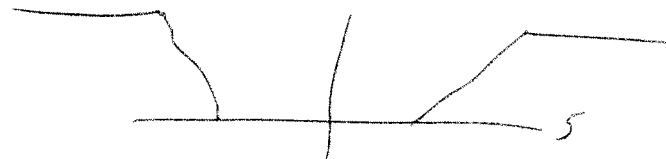
$$H(\xi = \pm\infty) = 0$$



HIGH PASS

$$H(\xi=0) = 0$$

$$H(\xi = \pm\infty) = 1$$



BANDPASS, BANDSTOP, BANDBOOST, HIGHBOOST, ...

PHASE - ONLY FILTERS (ALLPASS)

10/28 (10)

$$H(\xi) = \underline{1(\xi)} e^{+i\bar{\Phi}_H(\xi)}$$

$$G(\xi) = F(\xi) \cdot H(\xi) \Rightarrow |G(\xi)| = |F(\xi)| \cdot |H(\xi)|$$
$$\bar{\Phi}_G(\xi) = \bar{\Phi}_F(\xi) + \bar{\Phi}_H(\xi)$$

$$|G(\xi)| = |F(\xi)|$$

$$\bar{\Phi}_G(\xi) = \bar{\Phi}_F(\xi) + \bar{\Phi}_H(\xi)$$

NONLINEAR PHASES ARE BAD

POWER TRANSMISSION OF FILTERS

10/28 (11)

PARSEVAL'S THEOREM

$$\int_{-\infty}^{+\infty} |f(x)|^2 dx = \int_{-\infty}^{+\infty} |F(\xi)|^2 d\xi$$

$$G(\xi) = F(\xi) \cdot H(\xi)$$

$$\int_{-\infty}^{+\infty} |f(x) \otimes h(x)|^2 dx = \int_{-\infty}^{+\infty} |G(\xi)|^2 d\xi = \int_{-\infty}^{+\infty} |F(\xi) \cdot H(\xi)|^2 d\xi$$

SCHWARZ'S INEQUALITY

$$\left| \underset{\sim}{x} \cdot \underset{\sim}{y} \right| \leq \left| \underset{\sim}{x} \right| \cdot \left| \underset{\sim}{y} \right|$$

10/25 (12)

$$\int_{-\infty}^{+\infty} |F(\xi) H(\xi)|^2 d\xi \leq \int |F(\xi)|^2 |H(\xi)|^2 d\xi$$

$$\int_{-\infty}^{+\infty} |g(x)|^2 dx \leq \int |F(\xi)|^2 |H(\xi)|^2 d\xi$$

IF $|F(\xi)| |H(\xi)| \leq 1$ $\int |g(x)|^2 dx \leq \int |F(\xi)|^2 d\xi = \int |f(x)|^2 dx$

(DOES NOT AMPLIFY
ANY FREQ. COMPONENTS)
(PASSIVE FILTER)

~~$$|f(x)|^2 \leq |g(x)|^2$$~~

$$\int_{-\infty}^{+\infty} |g(x)|^2 dx \leq \int_{-\infty}^{+\infty} |f(x)|^2 dx$$

INTEGRATED "BRIGHTNESS"
OF OUTPUT \leq INTEGRATED BRIGHTNESS
OF INPUT

10/28 - (13)

$$f(x) = \delta(x) = 1 \cdot \delta(x)$$

$$|f(x)|^2 = \delta(x)$$

$$H(\xi) = \cancel{2\xi} \cancel{2\xi}$$

$$= \frac{1(\xi) e^{+2\pi i \xi}}{1}$$

$$h(x) = \delta(x+1)$$

$$g(x) = \delta(x) \times \delta(x+1) = \delta(x+1)$$

$$|g(x)|^2 = \delta(x+1) \neq |f(x)|^2$$

$$|f(x)|^2 \neq |g(x)|^2$$

$$\int_{-\infty}^{+\infty} |f(x)|^2 dx = 1 = \int_{-\infty}^{+\infty} |f(x)|^2 dx$$

$$\int_{-\infty}^{+\infty} |f(x)|^2 dx = \int_{-\infty}^{+\infty} |g(x)|^2 dx$$

$$\text{IF } H(\xi) = 1(\xi) e^{\underline{\underline{+i\Phi_H(\xi)}}} \Rightarrow$$

10/28 - (14)

"MAGNITUDE" FILTERS

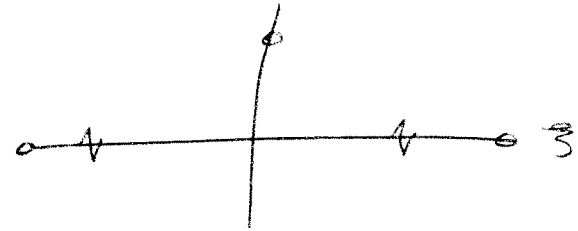
$H(\xi)$ is REAL-VALUED

LOWPASS FILTER

$$H(0) = 1$$

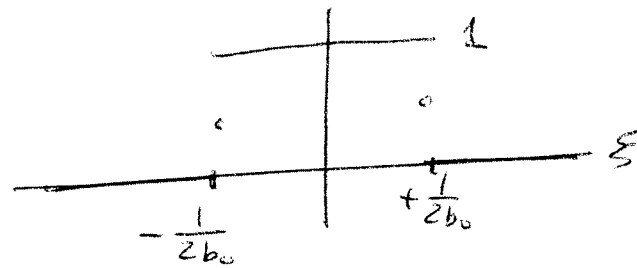
$$H(\xi = \pm\infty) = 0$$

$H_{LP}(\xi)$



$$H_1(\xi) = \text{RECT}\left(b_0 \frac{\xi}{\xi_c}\right) = \text{RECT}\left(\frac{\xi}{b_0^{-1}}\right)$$

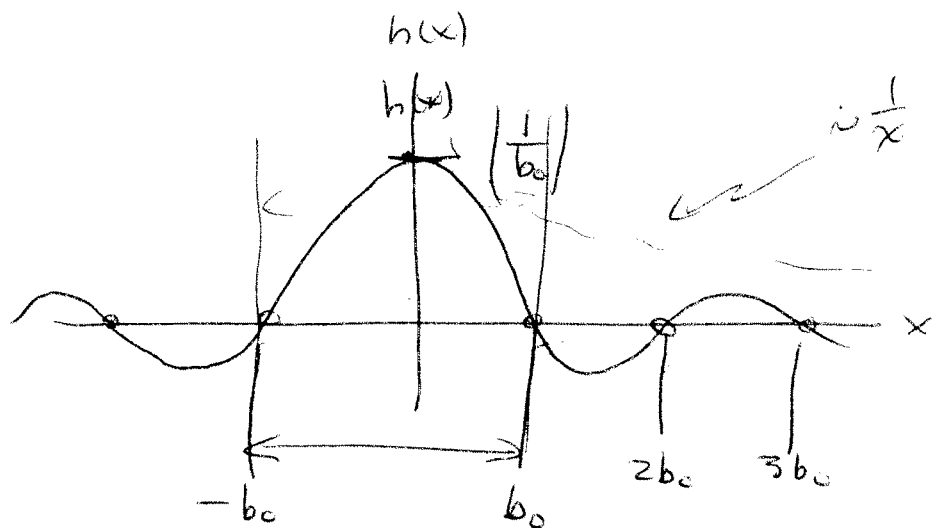
PASSES SINUSOIDS w/o CHANGE UP TO CUTOFF FREQ



$$\xi_{\text{CUTOFF}} = \frac{1}{2b_0}$$

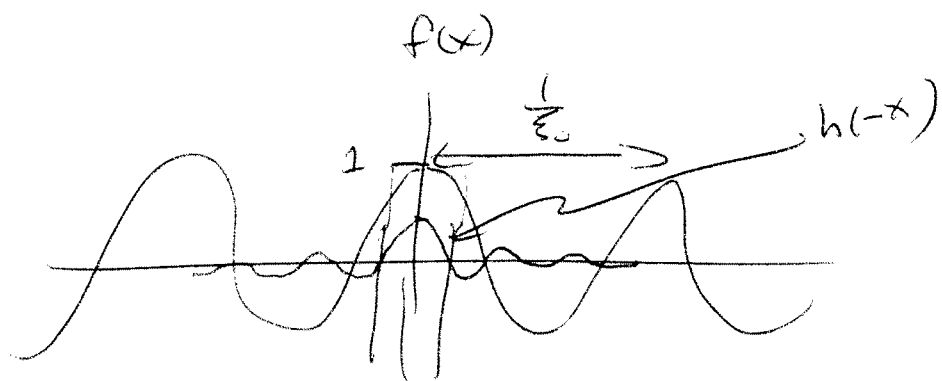
$$h_1(x) = \frac{1}{|b_0|} \text{SINC}\left(\frac{x}{b_0}\right) \Rightarrow \int_{-\infty}^{+\infty} h(x) dx = H(0) = 1$$

10/28 (15)



INFINITE SUPPORT

FOR $|x| \approx 0$ (NEAR ORIGIN), AMPLITUDE OF $h(x)$ IS POSITIVE



IN VICINITY OF ORIGIN
ALL VALUES OF $h(x)$ HAVE
SAME SIGN \Rightarrow LOCAL WEIGHTED SUM
 \Rightarrow LOCAL AVERAGE

10/28 - (16)

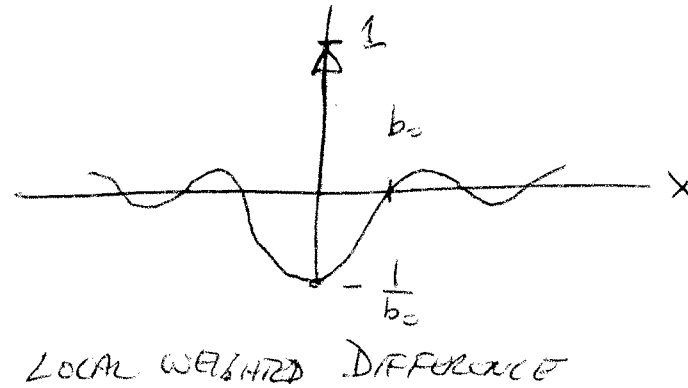
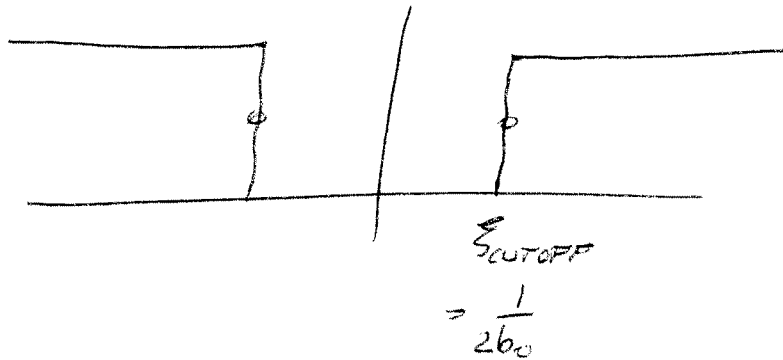
COMPLEMENT OF LOWPASS FILTER

$$H_{HP}(\xi) = 1(\xi) - H_{LP}(\xi)$$

$$h_{HP}(x) \implies \delta(x) - h_{LP}(x)$$

$$H_{LP}(\xi) = \text{RECT}\left(\frac{\xi}{b_0}\right) \implies h_{LP}(x) = \frac{1}{b_0} \text{SINC}\left(\frac{x}{b_0}\right)$$

$$H_{HP}(\xi) = 1 - \text{RECT}\left(\frac{\xi}{b_0}\right) \implies h_{HP}(x) = \delta(x) - \frac{1}{b_0} \text{SINC}\left(\frac{x}{b_0}\right)$$



10/28 (17)

RULE OF THUMB:

LOWPASS FILTER \Rightarrow LOCAL WEIGHTED SUM
 $=$ LOCAL AVERAGE
 \rightarrow REDUCE VARIABILITY OF AMPLITUDES
 \Rightarrow (PUSHES AMPLITUDES TOWARDS MEAN)

HIGH PASS FILTER \Rightarrow LOCAL DIFFERENCER
 \Rightarrow INCREASE VARIABILITY OF AMPLITUDES

BANDPASS FILTER \Rightarrow DIFFERENCES OF LOCAL AVERAGES

$$h(x) = \cos(2\pi\xi_0 x)$$

